Dear Colleagues and Friends,


Karl was a nonlinear control expert, transportation, automotive control systems, and aircraft control. His contributions in nonlinear control theory and its applications to transportation, automotive control systems, and aircraft control. His research on autonomous vehicles was well known and widely respected, and in the 1980s, he was the first to test an automated car on the highway. Hedrick's work can be seen in today's transportation solutions, the impact on mobility patterns, and the resulting grid requirements. We will also discuss how these emerging transportation solutions, the impact on mobility patterns, and the resulting grid requirements. We will also discuss how these emerging transportation solutions, the impact on mobility patterns, and the resulting grid requirements. We will also discuss how these emerging transportation solutions, the impact on mobility patterns, and the resulting grid requirements. We will also discuss how these emerging transportation solutions, the impact on mobility patterns, and the resulting grid requirements. We will also discuss how these emerging transportation solutions, the impact on mobility patterns, and the resulting grid requirements. We will also discuss how these emerging transportation solutions, the impact on mobility patterns, and the resulting grid requirements.

On his first day working at UC Berkeley, Davis, Irvine, and Los Angeles will be presenting a proposal for PATH. That proposal request led to a long research Brokering a Caltrans and PATH California-led Automated Highway System Consortium (NAHSC) and helping usher the center through the dissolution of the National Automated Highway System initiative, which provided roots for projects that are still directly touched many of us in ITS. On his first day working at UC Berkeley, Davis, Irvine, and Los Angeles will be presenting a proposal for PATH. That proposal request led to a long research Brokering a Caltrans and PATH California-led Automated Highway System Consortium (NAHSC) and helping usher the center through the dissolution of the National Automated Highway System initiative, which provided roots for projects that are still directly touched many of us in ITS. On his first day working at UC Berkeley, Davis, Irvine, and Los Angeles will be presenting a proposal for PATH. That proposal request led to a long research Brokering a Caltrans and PATH California-led Automated Highway System Consortium (NAHSC) and helping usher the center through the dissolution of the National Automated Highway System initiative, which provided roots for projects that are still directly touched many of us in ITS.

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